

# User Manual

# Line Scan Camera

# XCM40170DLMT2CXP





NIPPON ELECTRO-SENSORY DEVICES CORPORATION

## For Customers in U.S.A.

This equipment has been tested and found to comply with the limits for a Class A digital device, in accordance with Part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference when the equipment is operated in a commercial environment. This equipment generates, uses, and can radiate radio frequency energy and, if not installed and used in accordance with the instruction manual, may cause harmful interference to radio communications. Operation of this equipment in a residential area is likely to cause harmful interference, in which case the user will be required to correct the interference at his or her own expense.

### For Customers in the EU

This equipment has been tested and found to comply with the essential requirements of the EMC Directive 2004/108/EC, based on the following specifications applied:

#### **EU Harmonised Standards**

EN55022: 2010 Class A EN61000-6-2: 2005

#### Warning

This is a class A product. In a domestic environment this product may cause radio interference in which case the user may be required to take adequate measures.

#### Directive on Waste Electrical and Electronic Equipment (WEEE)

Please return all End of Life NED products to the distributor from whom the product was purchased for adequate recycling and / or disposal. All costs of returning the Product to NED are borne by the shipper.

# Introduction

Thank you for purchasing NED's Line Scan Camera. We look forward to your continued custom in the future.

## For safety use

- For your protection, please read these safety instructions completely before operating the product and keep this manual for future reference.
- The following symbols appear next to important information regarding safe product handling.



# Safety precaution



- Never disassemble or modify this product, unless otherwise specified to do so in this manual.
- When hands are wet, avoid handling this product and do not touch any of the connection cable pins or other metallic components.
- Do not operate this product in an environment that is exposed to rain or other severe external elements, hazardous gases or chemicals.
- If the product is not to be used for an extended period of time, as a safety precaution, always unplug the connection cable from the camera unit.
- If the product installation or inspection must be executed in an overhead location, please take the necessary measures to prevent the camera unit and its components from accidentally falling to the ground.
- If smoke, an abnormal odor or strange noise is emitted from the camera unit, first turn OFF power, then unplug the cable from the camera unit.
- This product is not intended for use in a system configuration built for critical applications.

# Instructions before use

- Only operate this product within the recommended environmental temperature range.
- Use only the specified power source and voltage rating.
- Do not drop this product. Avoid exposure to strong impact and vibrations.
- Install the camera unit in a well-ventilated environment, in order to prevent the camera from overheating.
- If the camera must be installed in an environment containing dust or other particles, take required measures to protect the camera unit from dust adhesion.
- Do not unplug the cable while power is being supplied to the camera unit. To prevent product damage, always shut down the power supply before unplugging the power cable.
- When the surface of the camera window becomes dirty due to dust or grime, black smudges appear in the displayed image. Use an air blower to remove the dust particles. Dip a cotton swab into ethanol alcohol and clean the camera window. Be careful not to scratch the glass.
- Use of non-infrared lighting such as a daylight fluorescent lamp is recommended. If halogen lighting is employed, always install an infrared filter into your system configuration.
- Please note that exposure to long wavelength light outside of the sensors visible optical range can affect the image.
- Sensitivity may fluctuate depending on the spectral response level of the light source. In cases like this, changing the light source to one with a different spectral response level may reduce this problem.
- Please note that when the sensor is exposed to excessive quantities of light, blooming may
  occur.because this product does not have a special Anti-Blooming function.
- For stabilized image capturing, turn on the power supply and execute aging for ten to twenty minutes before actually using the camera unit.
- Do not share the power supply with motor units or other devices that generate noise interference.
- Do not disconnect the camera while rewriting the embedded memory.
- When you change the exposure mode that is set at the NED factory, input control signal (Trigger packet) from the capture board.

# **Product Warranty**

#### Warranty Period

- The product warranty period, as a general rule, is two years from purchase; however, for detailed conditions please contact the sales representative for your region/country.
- However, in some cases due to the usage environment, usage conditions and/or frequency of use, this warranty period may not be applicable.

#### Warranty Scope

- Product repair will be performed on a Return to Manufacturer basis. On-site maintenance will incur additional charges.
- If defects in material or workmanship occur during the warranty period, the faulty part will be replaced or repaired by us free of charge. Return shipping charges must be paid by the sender. However, the following cases fall outside of the scope of this warranty:

#### Exclusions from Warranty Coverage

- We will under no circumstances assume responsibility for the following cases: damage caused by fire, earthquake, other acts of a third party, other accidents, negligent or intentional misuse by the user, or other usage under extraordinary circumstances.
- Damages (e.g. loss of business profits, business interruption, etc.) resulting from use or non-use.
- Damages caused by use other than as described in this document.
- Damages resulting from malfunction due to a connected device.
- Damages resulting from repairs or modifications performed by the customer.

#### Fault Diagnosis

- As a general rule, in the first instance fault diagnosis should take the form of a telephone call or an email to enable us to assess the circumstances of the malfunction.
- However, depending on the customer's requests, we, or our agent, may require an additional fee for this service.

#### **Exclusion of Liability for Compensation for Missed Opportunities**

Regardless of whether within the warranty period or not, our warranty does not cover compensation for missed opportunities for our customers, or our customers' customers, caused by a fault of our products, nor for damage to products other than our own, or related business.

#### Note about Product Usage

This product has been designed and manufactured as a general-purpose product for general industry. In applications expected to be life-critical or safety-critical, the installer or user is requested to install double or triple failsafe systems.

#### **Repair Service Outline**

The cost of dispatching engineers etc. for repair service is not included in the price of purchased and supplied goods. On request, arrangements can be made separately.

#### Scope of Repair Service

The above assumes business dealings and usage to take place in the customer's region/country. In cases of business dealings and/or usage outside the customer's region/country, separate consultation is required.

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## **1 Product Outline**

#### 1.1 Features

- 4096pixels x 2 Dual line sensor, Data Rate 340MHz
- Pixel format 8bit/10bit conversion
- CoaXPress interface
- CXP-2(2.5 Gbps). Cable length up to about 100 m
- High-integrity data
- Real-time action
- Up Link trigger semantics
- Device Discovery
- GenICam correspondence

#### 1.2 Application

- Inspection of Transparent panels and PCBs
- Flat panel display inspection
- Inspection of glass and sheet-like objects
- Inspection of high speed moving objects
- This camera utilizes an Intelligent Transportation System
- Outdoor surveillance



Figure 1-2-1 Visual Inspection of PCBs

#### Applicable Object

COB, BGA and MCM printed circuit boards

#### **System Configuration**

- 1. Camera: Line scan camera
- 2. Controller: Dedicated software for PC system

#### Applicable Fields

Inspection of patterns on film PCBs

#### 1.3 Image Sensor

The camera uses a CMOS sensor with a maximum data rate of 340MHz to acquire high responsivity and superior quality images.

The sensor has pixels of 7µmx7µm in size and dual lines.

At TDI mode, the camera outputs 4096 pixels data through 340MHz-Dual, 170MHz-Single.

Also, it comes as the output data of 2048 pixels with  $14\mu$ m-square pixel equivalent from 170MHz by 2x2 pixels binning.



2048 pixels with 14µm-square pixel equivalent by 2x2 pixels binning



UME-0064-01

XCM40170DLMT2CXP

#### **1.4 Performance specifications**

The Performance Specifications are shown in Table 1-4-1. It shows the data when the camera is operating at maximum scan rate, unless otherwise specified.

	ltomo	Specifications		
	nems	XCM40170DLMT2CXP		
Number of Pixels			4096x2(Dual line)	
Pixel Size	H x V (μm)		7 x 7	
Sensor Leng	gth (mm)		28.672	
Data Rate (I	MHz)	34	40 (Dual)/ 170 (Single)	
Scan Rate		4096pixels/Dual	77.555 / 12.894	
(kHz) /(µs)	)	4096pixels/Single	39.795 / 25.129	
		2048pixels/Dual	76.505 / 13.071	
		2048pixels/Single	76.505 / 13.071	
Responsivit	y (V/[lx⋅s])typ.	100 *	Daylight Fluorescent Light	
[Minimum Gain,	Pixel Correction Initial Value]	* Analo	g 5V Conversion Sensitivity	
Gain Adjusta	able Range	Analog Am	olifier: x 1 to x 17.8 (8 Steps)	
*Analog Amplifie	r +Digital	D	igital: x 1 to x 2 (512 Steps)	
Digital Offse	et Adjustable Range	407.14		
*Digital		-127 to 127 (0.5DN / Steps): 8bit		
FPN		Typically 5% (without correction, at minimum gain)		
(Fixed Patter	rn Noise)	2%(with correction, at minimum gain)		
PRNU		Typically 8% (without correction, at minimum gain)		
(Photo Resp	onse Non Uniformity)	4%(with correction, at minimum gain)		
Dandam Naiss			Typically 10DN	
Random No	lise	(peał	value at minimum gain)	
Video outpu	t		CoaXPress Ver.1.0	
Control Inpu	ıt	Control Packet	(Camera control) / Trigger Packet	
Connectore	Data/Controller	Cana	are : BCJ-FPC (75Ω) x2	
Connectors	Power Supply	Hi	rose : HR10A (6Pin)	
Lens Mount		Standard: F Mount		
Operating T	Operating Temperature (°C)		0 to 50	
No Condens	sation			
Power Supp	bly Voltage (V)		DC12~15[±5%]	
(typically) 400(DC12V)		400(DC12V)		
Size W x H x D (mm) 60 x 100 x 36		60 × 100 × 36		
Mass (g) (	Camera only)	Approx. 340(without Lens mount)		

 Table 1-4-1
 Performance Specifications

XCM40170DLMT2CXP

UME-0064-01

NED	10
Additional Function	1. Two-line TDI
	2. Gain/Offset Adjustable
	3. Test Pattern Output On / Off
	4. Programmable Exposure Control
	5. Scan Direction Switching

Note:

\*1) DN : Digital Number (8bit : 0-255)

\*2) Measurements were made at room temperature.

Itoms	Interface specifications			
lienis	XCM40170DLMT2CXP			
Bit Rate	2.5Gbps (CXP-2)			
Discovery Rate	1.25Gbps (CXP-1) (at Device discovery)			
Number of Links	2(2 cables): Dual mode	1(1 cable):Single mode		
PoCXP	Not Used			
Pixel Format	Mono8, Mono10			
Image Type	Rectangular			
Low Speed Link Trigger	Grabber(Host) $\rightarrow$ Camera(Device), Jitter ±8ns			

The spectral responsivity is shown below.



Quantum efficiency

# 2 Camera Setting and Optical Interface

#### 2.1 Setting the Camera

Use the M4 screw holes or the tripod screw hole to set the camera.

#### 2.2 Fixing the Camera

Use the M4 screw holes (4 places at the front, 8 places at the side) to set the camera.

Or use the 1/4"-20UNC screw hole for a tripod (1 place at side).

If using the front panel M4 mounting holes (4 places at the front, 8 places at the side), the screw length for fixing the camera should be less than 6mm.

No X-, Y-axis orientation and tilt adjustment mechanism is available. Please prepare an adjustment mechanism if required.

The dimensions of the camera are shown below.





#### 2.3 Optical Interface

The XCM40170DLMT2CXP comes with an F-Mount as standard.

1) Quantities of light and the wavelength etc. of a source of light necessary to take the image for which the customer hopes are different according to the usage. The factor to decide these contains physical properties, the speed, the spectrum characteristic of the object taken a picture of, the exposure time, and the characteristic of the source of light and the specification etc. of the taking system. It is a luminous exposure (exposure time × quantities of light) that it is important because an appropriate image is obtained. Please decide the exposure time and quantities of light after examining which element the customer values enough.

- 2) Keep these guidelines in mind when setting up your light source:
- LED light sources are relatively inexpensive, provide a uniform field and longer life span compared to other light sources. However, they also require a camera with excellent sensitivity.
- Halogen light sources generally provide very little blue light but have high infrared light (IR) proportions.
- Fiber-optic light distribution systems generally transmit very little blue light relative to IR.
- Metal halide light sources are very bright but have a shorter life span compared to other light sources.
  - 3) Generally speaking, the brighter light sources, the shorter life span.

CMOS image sensors are sensitive to infrared (IR). We recommend using daylight color fluorescent lamps that have low IR emissions. If you use a halogen light source, to prevent infrared from distorting the images use an IR cut off filter that does not transmit wavelengths.

## 3 Hardware

#### 3.1 Camera Connection



Figure 3-1-1 Connections between Camera and Frame Grabber Board

• Depending on the frame grabber board, up to two cameras can be connected.

<Note : Choosing a suitable coaxial cable>

Please use a  $75\Omega$  coaxial cable with a BNC connector according to the CoaXPress standard. The maximum cable length is not prescribed by the standard. The maximum cable length to be able to transfer data depends on factors such as attenuation, diameter and manufacturer.

We recommend that you use a standard approved cable.

Refer to JIIA (<u>http://jiia.org/cxp/</u>) for more information about standard approved cables.

As specifications for each manufacturer differs, please contact the cable manufacturer directly for details.

#### 3.2 Input / Output Connectors and Indicator

The layout of input /output connecters and the indicator lamp are as follows.



Figure 3-2-1 Input/output Connectors and Indicator

The pin assignment of the power supply connector is shown below.





• Round shape push-pull lock type

#### Table 3-2-1 Pin Assignment of Power Supply Connector

Ν	lo	Name
	1	12-15V
4	2	12-15V
	3	12-15V
4	1	GND
Ę	5	GND
6	6	GND

#### 3.3 Power Supply

The camera requires a single power supply (DC+12 to +15V).

When selecting a power source, choose one with the capacity to allow for inrush current. (10W or more recommended)

Insert the cable plug securely until it locks into position. This is to prevent the connector from coming loose during power transmission.
 Compatible Cable (Compatible plug): DGPSH-10 (HIROSE: HR10A-7P-6S)

Power supply voltage: DC+12-+15V (+/-5%)

Consumption Current (rated): DC+12V: 400mA

- The LED lamp illuminates when +12V to +15V power is being supplied to the camera.
- If the lamp fails to illuminate even after power is supplied, turn off power immediately.
   Inspect wiring. Check the voltage and capacity of the supplied power source.

#### **3.4 LED Indicator Status**

Camera Power Supply is off	:	LED off
Camera Booting Up (Power On)	:	Lights orange
Device Discovery	:	Lights orange for 0.5s
Scan rate > about 1.5s*	:	Blinks orange (Except ExtEdge Mode)
Low Speed Link disconnected (Cable d	isc	connected) : Lights red
Unable to process commands (System	cra	ash) : Blinks red
Transmitting image packets (Acquisition	n St	Start =1) : Lights green
Not transmitting image packets (Acquis	itio	on Stop =1) : Blinks green

- \* When the scan rate is close to 1.6s, the LED may flash orange and green alternately. When Acquisition Start and Stop are performed repeatedly, the green LED may appear to be flashing.
- \* Moreover, when repeating the operation rapidly, the green LED may appear dark.

## 4 Camera Startup

#### 4.1 Camera Startup Procedure

This camera does not immediately output stream data packets (image data) after powering on. In order to output stream data packets, it is necessary to perform Device Discovery (Camera and Frame Grabber connection).

Please check your frame grabber's manual for how to perform device discovery.

The below example uses Matrox's Radient eV-CXP as an example. The Radient eV-CXP performs device discovery on opening a "DCF" file.

①Open Intellicam from the Matrox Imaging Library



②From the Intellicam "File/Open" Menu, open "DefaultLineScan"

Matrox Intellicam • Edit View Digitizer Options Window Help				
) 📓 🎽 🚽 🗸 📾 📾 🛱 💭 🗐	Image:	Radient eV-CXP 0	•	6
開く				X
ファイルの場所(D: 🔒 dcf	- G 👌 🖻 🖽 -			
名前	更新日時	種類	サイズ	
🗑 cxp_xcm60160cxp_el_fls.dcf	2015/12/11 11:15	Intellicam DCF files	2 KB	L
s.dcf	2013/12/27 15:05	Intellicam DCF files	2 KB	
🗑 DefaultLineScan.dcf	2012/10/01 15:25	Intellicam DCF files	1 KB	
DeraultEineScan_ExtLevel.dcf	2013/12/27 13:38	Intellicam DCF files	2 KB	
📱 DefaultLineScan_XCM16K04GT4CXP_140305	2014/03/05 17:04	Intellicam DCF files	2 KB	
🗑 DefaultLineScan-2K.dcf	2014/07/03 17:54	Intellicam DCF files	2 KB	
Dofnulti inoConn. 417 dof	1015/10/17 0:40	Totallian DCE Alas	21/0	1
7ァイル名(N): DefaultLineScan.dcf			開((0)	
	wether the state of the second second	1	*****	

③If the contents of the DCF file are displayed, then discovery has been performed successfully.

## **5 Camera Control**

The camera can be controlled by the frame grabber board through the camera's control registers. The camera supports GenlCam, and so can be easily controlled by a GenlCam-compatible frame grabber. The camera control software which came with your frame grabber should be used for camera control.

Once the camera settings have been made and saved, the camera will operate without further setting.

#### 5.1 Flow of Camera Control

#### 5.1.1 GenICam overview

- The camera control register information is saved inside the camera (XML file)
- The frame grabber board reads the XML file during Discovery, and acquires the register information.
- Camera control is enabled after Discovery.

#### 5.1.2 Camera Control registers

The camera can be controlled the function through camera register by frame grabber board.

Control Item	Address	R/W	VAL	Control Description	
Category : Device Control					
	0x0000_20C0				
Device User ID	$\sim$	R/W	(ASCII code)	User define ASCII code	
	0x0000_20CF				
Category : CoaXPress					
CxpLinkConfig	0x0000_4014	R/W	0x10030/0x20030	Single CXP-2 / Dual CXP-2	
Category : Image Format Control					
W/idth	0~000 000	Р	2048 / 4006	Binning Horizontal=2, 2048 Pixels	
<b>WIGHT</b>	0X0000_A000	ĸ	2048 / 4096	Binning Horizontal=1, 4096 Pixels	
Height	0x0000_A004	R	1	1 Line	
	ing Horizontal 0x0000_A280 R/W 1 / 2		1/0	1=Off / 2=2 Pixels binning	
Dinning Horizontal		See 5.3.22			

Table 5-1-2-1 List of Camera Control Registers
--

				NED
NED_TDIMode	0x0000_A254	R/W	0/1/2/3	0=Dual line(average) / 1=Single line A / 2=Dual line(addition) / 3=Single line B See 5.3.22
PixelFormat	0x0000_A014	R/W	0x101 / 0x102	0x101=Mono8 / 0x102=Mono10
Category : Acquisition C	ontrol			
Acquisition Mode	0x0000_A008	R	0	Continuous
Acquisition Start	0x0000_A00C	R/W	0 to 1	0=Stop / 1=Start
Acquisition Stop	0x0000_A010	R/W	0 to 1	0=Start / 1=Stop
Category : Analog Contr	rol			
				0=Off(1.00) /
				1=Gamma 0.45 /
NED_GammaMode	0x0000_A258	R/W	0/1/2/3/4	2=Gamma 0.56 /
				3=Negative Positive inversion /
				4=Custom
Gamma	0x0000_A25C	R/W	250 to 4000	γ0.250~4.000
Category : NED Camera	features			
AnalogGain	0x0000_A080		0 to 7	x1.00x17.8
		R/11	0107	See 5.11
DigitalGain	0x0000_A084	R/W	0 to 511	x1x2(x0.003906/step)
			010511	See 5.11
				-6363(0.5DN/step at 8bit)
DigitalOffset	0x0000_A088	R/W	-127 to 127	-254254(2DN/step at 10bit)
				See 5.10
ExposureMode	0x0000_A08C	R/W	0 / 1 / 2	0=FreeRun / 1=ExtEdge / 2=ExtLevel
			915 to	Dual CXP-2 Binning Horizontal=1,
			1048575	10.765~12336.176µs
			1955 to	Single CXP-2 Binning Horizontal=1,
ExposureTimeCounter	0x0000 A094	RW	1048575	23.000~12336.176µs
Exposure rimeoounter	00000_0004	10/00	930 to	Dual CXP-2 Binning Horizontal=2,
			1048575	10.941∼12336.176µs
			930 to	Single CXP-2 Binning Horizontal=2,
			1048575	10.941~12336.176µs
Padding	0x0000_A098	R/W	0 to 1048575	2.129~12338.305µs
TestImageSelector	ΟχΟΟΟΟ ΔΟΔΛ	R/\/	0 / 1	0=Off / 1=GreyHorizontalRamp
	0.0000_A0A4			See 5.13
ReverseX	0x0000_A0B4	R/W	0 / 1	0=Forward / 1=Reverse

NED				
LineDelay	0x0000_A0E4	R/W	-1 / 0 / 1	Output delay adjustment between line datas Amount of line data -1/0/1 Note: when using line delay mode setting at -1 or1, NED_TDIMode must be set at 0 or 2 See 5.3.22
PixelCorrectSetMode	0x0000_A0A8	R/W	0/1/2/4/5	0=Disable (Factory Black) / 1=Factory white (Factory Black) / 2=User White (Factory Black) / 4=User Black + Factory white / 5=User Black + User white
PixelCorrectSetLevel	0x0000_A0AC	R/W	0 to 255	Correction Level(8bit)
PixelCorrectDataSave	0x0000_A0B0	W	1	Store pixel correction data in memory (White)
PixelCorrectDataSave Black	0x0000_A11C	W	1	Store pixel correction data in memory (Black)
PixelCorrectData_ ResetToFactoryDefault	0x0000_A260	W	1	Pixel correction data reset to factory settings
Category : User Set Con	itrol			
UserSet_ ResetToFactoryDefault	0x0000_A0B8	W	1	UserSet data reset to factory settings
UserSet_Load	0x0000_A0BC	W	1	Readout setup data in memory
UserSet_Save	0x0000_A0C0	W	1	Store present setup data in memory

#### 5.1.3 Memory Setup Values (Factory Settings)

The memory setup values (factory settings) are shown below.

Table 5-1-3-1	Memory Setup	Values	(Factory	Settings)
---------------	--------------	--------	----------	-----------

Control Item	Address	VAL	Control Description
Device User ID	0x0000_20C0	0x00	
CxpLinkConfig	0x0000_4014	0x20030	Dual CXP-2
Width	0x0000_A000	4096	4096 Pixels
Binning Horizontal	0x0000_A280	1	Horizontal Binning OFF
NED_TDIMode	0x0000_A254	0	Dual line(average)
PixelFormat	0x0000_A014	0x101	Mono8(8bit)
Acquisition Start	0x0000_A00C	0	Stop
Acquisition Stop	0x0000_A010	1	Stop
NED_GammaMode	0x0000_A258	0	Off(γ1.00)
Gamma	0x0000_A25C	1000	γ1.000
AnalogGain	0x0000_A080	0	x1.00
DigitalGain	0x0000_A084	0	x1.00
DigitalOffset	0x0000_A088	0	0
ExposureMode	0x0000_A08C	0	FreeRun
ExposureTimeCounter	0x0000_A094	10000	117.647µs
Padding	0x0000_A098	0	2.129µs
TestImageSelector	0x0000_A0A4	0	Off
ReverseX	0x0000_A0B4	0	Forward
LinoDolov		0	Line Delay 0
LineDelay	0x0000_A0E4	0	(Not use line delay)
PixelCorrectSetMode	0x0000_A0A8	1	Factory white (Factory Black)
PixelCorrectSetLevel	0x0000_A0AC	200	

# 5.2 Programmable Exposure Time • Exposure-Readout Time calculation procedure

Programmable Exposure Time ( $\mu$ s)=ExposureTimeCounter÷85.0 Exposure-Readout Time ( $\mu$ s)=2.129+{ Padding÷85.0 } Scan Rate( $\mu$ s)=Programmable Exposure Time+(Exposure-Readout Time)

Calculated example) ExposureTimeCounter :  $(0x0000\_A094) = 10000$ Padding :  $(0x0000\_A098) = 0$ 

Programmable Exposure Time =  $10000 \div 85.0 = 117.647 \mu s$ Exposure-Readout Time $= 2.129 + (0 \div 85.0) = 2.129 \mu s$ Scan Rate $= 117.647 + 2.129 = 119.776 \mu s$ 

#### 5.3 Details on register system

This explanation uses the Matrox Radient eV-CXP as an example.

①Run Intellicam (part of Matrox Imaging Library).



②Open the DCF file and the Feature Browser.

	Contract of the second s
t View Dcf Digitizer Options Window Help	
ItLineScan.dcf	
Disitizer Feature Control Advanced settings	
Jverview Description Camera Feature Control	
DEVE ADARGINADERIZOP RED	
Matrox	
Radient	
and Information	
NEW NED VOMBIZION MTX/VR	
n voc inscan	
PROF 3 (0) 4096 × 1	
guisiton Mode Continuous	
cel Format: Monoil	
vellicam version: 0009.0013.0000	
nt ev-CXP 0 Digitizer 0	

③Control the camera from the Features box.

😹 User L	evel:	Guru	-	]	🔄 Polling
Feature N	ame			Value	
NED XC	M401	70DLMT2	СХР		
🗄 Devi	ce Cor	ntrol			
E Coal	( Pres	s			
🗉 Ima	ge For	mat Cont	rol		
E Acq	isitio	n Control			
🗄 Ana	log Co	ntrol			
	Came	ra featur	es		
🗄 User	Set C	ontrol			
	facto	ry only			
HIL Sy	stem C	Controls			
🕀 MIL Dig	itizer	Controls			
e				ш	
eature pro	pertie	s:			
NED Camer	a featu	ires			Ľ
MIL API:	MIL_	INT64 Dig	gitalG	ain = 0;	
	MIL_	INT64 Dig	jitalC	iffset = 0;	
	MIL	INT64 Ex	posur	eTimeCounter = 10000;	
	MTI	TNITE4 Da	dding	0.	

In the case of the Matrox Radient, the list of registers is displayed in the window.
 Change the settings via the dropdown list or spinners.

#### 5.3.1 Setting LinkConfig

Sets Links of camera, Dual(2 cables)/Single(1 cable)

- Register name CxpLinkConfig
- VAL Single:CXP-2(2.500Gbps) / Dual: CXP-2(2.500Gbps)
   (Example) Single(1 cable)

CxpLinkConfig : Single:CXP-2(2.500Gbps)

CxpLinkConfig	Dual:CXP-2( 2.500 Gbps)		
CxpLinkConfigDefault	Single:CXP-2( 2.500 Gbps)		
CxpTestMode	Dual:CXP-2( 2.500 Gbps)		

After setting, run the memory save function in 5.3.21.

Also, need to re-discovery.

If you did not the memory saving, it will go back to the original setting value when the power is turned on again.

#### 5.3.2 Setting Horizontal Binning

Sets horizontal binning.

- Register name Binning Horizontal
- VAL 1 / 2 (Binning Off : 4096pixels / 2px Binning : 2048pixels)
- (Example) 2px Binning (2048 pixels)

Binning Horizontal : 2

By setting value, it will change the width.

😑 Image Format Control	
Width	2048
Height	1
Binning Horizontal	2
NED_TDIMode	Dual line(average)
PixelFormat	Mono8

#### 5.3.3 Setting TDI mode

Sets TDI mode.

- Register name NED\_TDIMode
- VAL 0/1/2/3

(Dual line(average) / Single line A / Dual line(addition)

/ Single line B)

(Example) Dual line mode(Additional average)

NED\_TDIMode : Dual line(average)

Image Format Control	
Width	2048
Height	1
Binning Horizontal	2
NED_TDIMode	Dual line(average)
PixelFormat	Dual line(average)
Tap Geometry	Single line A
Image1StreamID	Dual line(addition)
Image2StreamID	Z Z

#### 5.3.4 Setting Pixel Format

Sets pixel format of camera.

- Register name PixelFormat
- VAL Mono8 / Mono10

(Example) Mono 8bit

Pixel Format : Mono8

PixelFormat	Mono8	-
Tap Geometry	Mono8	
Image1StreamID	Mono10	

#### 5.3.5 Setting Gamma Correction

Sets gamma correction.

- Register name NED\_GammaMode
- VAL 0 / 1 / 2 / 3 / 4 (Off(γ1.00) /γ0.45 /γ0.56 / Negative Positive inversion / Custom)
   Register name Gamma (Custom mode only)
- VAL
   0.250 to 4.000 (γ0.250~4.000)

(Example) Custom γ0.3

NED\_GammaMode : Custom

Gamma : 0.3

NED_GammaMode	Custom
Gamma	0.300000

#### 5.3.6 Setting Analog Gain

Sets analog gain between x1 and x17.8.

- Register name AnalogGain
- VAL x 1 ~ x 17.8
   (Example) Setting analog gain[X 5.2]
  - AnalogGain : x 5.2(14.3dB)

🚽 User Level: 🛛 🖓 Guru	🗖 Polling
Feature Name	Value
NED Camera features	
AnalogGain	x 1.0 ( 0.0dB) 👻
DigitalGain	x 1.0 ( 0.0dB)
DigitalOffset	x 1.8 ( 5.0dB)
ExposureMode	x 3.4 (10.7dB)
Clock	x 6.4 (16.1dB)
ExposureTimeDividing	x 7.80 (17.9dB)
ExposureTimeCounter	x 9.7 (19.7dB)
Padding	x17.8 (25.0dB)

#### 5.3.7 Setting Digital Gain

Sets digital gain in 512 steps between x1 and x2

```
Digital Gain : 1023 / (1023 – VAL)
```

- Register name Digital Gain
- VAL 0 (x1)~511 (x2)

(Example)

Digital Gain: 255 (Setting digital gain 255(1023/(1023-255)=x1.33)

NED Camera features	
AnalogGain	x 1.0 ( 0.0dB)
DigitalGain	255
DigitalOffset	5
ExposureMode	Free run
Clock	85.0

#### 5.3.8 Setting Digital Offset

Sets digital offset -127~+127(8bit : 0.5DN/Step), -127~+127(10bit : 2DN/Step)

- Register name DigitalOffset
- VAL -127 ~ +127

(Example)

Digital Offset: 5

NED Camera features	
AnalogGain	x 1.0 ( 0.0dB)
DigitalGain	255
DigitalOffset	5
ExposureMode	Free run
Clock	85.0

#### 5.3.9 Setting Exposure Mode

Sets the exposure mode.

- Register name ExposureMode
- VAL Free run / External edge / External level

(Example)

ExposureMode: Free run

NED Camera features		
AnalogGain	x 1.0 ( 0.0dB)	
DigitalGain	255	
DigitalOffset	5	
ExposureMode	Free run	÷
Clock	Free run	
ExposureTimeDividing	External edge	
ExposureTimeCounter	External level	

#### 5.3.10 Setting Exposure Time

Sets the exposure time.

- Register name ExposureTimeCounter
- VAL 915~1048575 (Setting Counter)
  - (Example)

ExposureTimeCounter : 10000

The changes will be reflected in Integration Time and Scanrate.

ExposureMode	Free run	
Clock	85.0	
ExposureTimeDividing	0	
ExposureTimeCounter	10000	
Padding	0	
IntegrationTime	117.647	
FixedBlanking	2.129	
	110 776	

#### 5.3.11 Setting Exposure-Readout Time

Sets exposure-readout time.

- Register name Padding
- VAL 0~1048575
  - (Example)
  - Padding : 200

The changes will be reflected in Padding Time and Scanrate.

ExposureMode	Free run	
Clock	85.0	
ExposureTimeDividing	1	
ExposureTimeCounter	10000	
Padding	200	
IntegrationTime	117.647	
PaddingTime	2.353	
FixedBlanking	2.129	
Scanrate	122.129	

#### 5.3.12 Generating Test Pattern

Generates test pattern.

- Register name Test Image Selector
- VAL Off / GreyHorizontalRamp

(Example)

TestImageSelector: GreyHorizontalRamp

TestImageSelector	Off 🗸
PixelCorrectSetMode	Off
PixelCorrectSetLevel	GreyHorizontalRamp

#### 5.3.13 Setting Pixel Readout Direction

Sets the pixel readout direction.

- Register name ReverseX
- VAL clear the check box(Forward) / check box (Reverse)

(Example)

ReverseX : Check box

TestImageSelector	Off
ReverseX	
LineDelay	0

#### 5.3.14 Setting Line Delay

Sets line delay when TDI mode is "Dual line".

- Register name LineDelay
- VAL -1/0/1

(Example) Line Delay 1

LineDelay : 1

ReverseX		
LineDelay	1	
PixelCorrectSetMode	Factor	y white

#### **5.3.15 Setting Pixel Correction**

Sets pixel correction.

- Register name Pixel Correct Set Mode
- VAL Disable / Factory white / User white / User Black + Factory white / User Black + User white
- Register name Pixel Correct Set Level
- VAL 0 ~ 255 (Setting correction level: 8bit)
  - (Example) : for Factory white, correction level 127
    - PixelCorrectSetMode : Factory white

PixelCorrectSetLevel : 127

LineDelay	0	
PixelCorrectSetMode	Factory white	2
PixelCorrectSetLevel	127	
PixelCorrectDataSave	Execute()	
PixelCorrectDataSaveB	Execute()	

#### 5.3.16 Getting User White

Gets arbitrary user white data, save the memory.

- Register name PixelCorrectDataSave
- VAL Execute()

PixelCorrectDataSave	Execute()	
PixelCorrectDataSaveB	Execute()	

#### 5.3.17 Getting User Black

Gets arbitrary user black data, save the memory.

- Register name PixelCorrectDataSaveBlack
- VAL Execute()

PixelCorrectDataSave	Execute()
PixelCorrectDataSaveBlack	Execute()
PixelCorrectData_ResetToF	Execute()

#### 5.3.18 Reset User White-Black

After reset the user white-black correction data, return to the factory value. To reset, it takes about 1 minute.

Please do not turn off the camera until the command is completed.

- Register name PixelCorrectData\_ResetToFactoryDefault
- VAL Execute()

PixelCorrectDataSaveBlack Execute()	PixelCorrectDataSaveBlack	Execute()
-------------------------------------	---------------------------	-----------

#### 5.3.19 Memory Initializing (Initializing Camera Settings)

Reset the flash memory to the factory default.

- Register name User Set\_Reset to Factory Default
- VAL Execute()



#### 5.3.20 Memory Load (Reads out the camera settings from the flash memory)

Reads out the camera settings from the flash memory

- Register name User Set\_Load
- VAL Execute()



#### 5.3.21 Memory Save

Stores current camera settings in the flash memory.

- Register name User Set\_Save
- VAL Execute()

UserSet\_Save Execute()

### 5.3.22 Setting Line Delay, TDI mode by the horizontal binning

To this camera, as a horizontal binning function, there are two types of Binning Off(4096pixels) and 2pixel Binning(2048pixels).

It summarizes how to set LineDelay and NED\_TDIMode to be related Binning Horizontal in the following Table.

Binning	LineDelay	NE	D_TDIMode	Description
Horizontal				
1	0	0	Average	Purpose : Improvement S/N ratio
Binning	No delay			Pixel size : 7x14um
Off		1	A-line output	Output A-line only
		2	Addition	Purpose : Improvement Responsivity
				Pixel size : 7x14um
		3	B-line output	Output B-line only
	1	0	Average	Improvement S/N ratio
	Setting	1	-	_
	1line delay	2	Addition	Improvement Responsivity
	(Forward)	3	-	-
	-1	0	Average	Improvement S/N ratio
	Setting	1	—	-
	1line delay	2	Addition	Improvement Responsivity
	(Reverse)	3	_	-
2	0	0	Average	Improvement S/N ratio
2pixels	No delay			(Output signal is average of 4pixels)
Binning				Pixel size is 14x14um
		1	1	_
		2	Addition	Improvement Responsivity
				(Output signal is digital added of 4pixels)
				Pixel size is 14x14um
		3	_	_
	1	0	_	_
	Not use	1	_	_
		2	_	_
		3	_	_
	-1	0	_	-
	Not use	1	_	_
		2	_	_
		3	_	_

Table 5-3-22-1 Setting Line Delay, TDI mode by the horizontal binning

#### 5.4 Digital Processing flow in FPGA

The figure below shows the digital processing flow in the FPGA.

#### FPGA Processing block diagram



In Test Pattern mode, Black /White reference and Digital Gain/Offset will be skiped.

Figure 5-4-1 FPGA Processing Block Diagram

#### 5.5 Startup

When you power on the camera, the camera goes through a series of startup procedures. During startup, the LED lights orange.

The startup procedure is as follows.

 ${\rm (I)}$  The camera initializes the hardware.

② Reads out the latest camera settings from the flash memory. (User settings if any or factory default settings)

③ Sets up the camera with the setting values from the flash memory.

When this sequence finishes, the camera is ready to capture and output images. In order to output images, the Discovery procedure must be done from the frame grabber board.

#### 5.6 Saving and Loading Camera Settings

The camera setting data is saved in the internal memory (flash memory) and is loaded from the memory when turning on the power supply or loading.

The number of times the flash memory can be rewritten will vary depending on actual operational conditions. After turning on the power supply, the camera always checks the memory status. If the data is not within the designated range due to a malfunction or other type of trouble, the memory will be automatically rewritten with the factory settings.

If disconnecting camera power while rewriting the memory, all data saved in the memory will be deleted.

As it takes several seconds to rewrite the memory, do not disconnect the power supply before receiving the response from the camera.

Registers for rewriting the memory are as follows.

- Get Pixel Correction User-white data (PixelCorrectDataSave)
- Get Pixel Correction User-black data (PixelCorrectDataSaveBlack)
- Reset to factory setting (PixelCorrectData\_ResetToFactoryDefault)
- Initialize memory (Userset\_ResetToFactoryDefault)
- Save memory (Userset\_Save)
- When changing the factory setting exposure mode, be sure to send the control input signal (Trigger packet) from the frame grabber board. If you do not send or sending control input signals are out of the designated range, you cannot get images and cannot change the setting. See 5.9.2 and 5.9.3.

#### Table 5-6-1 Camera Operation Mode and Control Input

Camera operation mode	Control input
(Exposure mode)	(from frame grabber board)
Free Run (Programmable time setting)	Not in use
(Factory Setting)	NOT IN USE
Ext Edge (External trigger edge+ Programmable	External trigger (Trigger peaket) is required
time setting)	External trigger (Trigger packet) is required
Ext Level (External trigger level time setting)	External trigger (Trigger packet) is required

#### 5.7 Video Output Format

The camera outputs 8-bit or 10-bit black and white digital data(Pixel Format : Mono 8 or Mono 10) through CoaXPress IF.



Figure 5-7-1 Assignments of Digital Data

The A/D converter of the camera has a 10-bit resolution. For 8-bit output, the upper 8-bit signal can be output as a video data.

#### 5.8 XML file

The XML file is a file saved in the camera which contains the register information described in chapter 5.

According to the CoaXPress specification, when "Device Discovery" is performed from the camera control software supplied with the frame grabber, this file is read out, and the camera control registers are displayed in the camera control software (in the case of some manufacturers, they may not be displayed)

• However, if the frame grabber does not support GenICam, this function is not available.

#### 5.9 Exposure Mode and Timing Chart

The camera has three exposure modes. The overview of each mode and the timing are as follows.

#### 5.9.1 Free Run Exposure Mode

In free-run exposure mode, the camera generates its own internal control signal based on two programmable parameters, exposure time and readout time.

		4096pixels_Dual	10.765~12336.176
	4096pixels_Single	23.000~12336.176	
Ρ	p Programmable exposure time	2048pixels_Dual	10.941~12336.176
		2048pixels_Single	10.941~12336.176
		4096pixels_ Dual	12.05
r Readout time	4096pixels_ Single	24.09	
	2048pixels_ Dual	12.05	
		2048pixels_ Single	12.05

#### Table 5-9-1-1 Free Run Programmable Exposure Time



Figure 5-9-1-1 Free Run Exposure Mode(In case of 4096 pixels)

• The data of Exposure (1) is read out at Readout (1)

(Unit:µs)



Figure 5-9-1-2 Free Run Exposure Mode(In case of 2048 pixels)

#### 5.9.2 External Trigger Exposure Mode (Trigger Edge)

In external trigger exposure mode (Trigger Edge), the exposure time is determined by setting the control register, and the line period is determined by the external trigger period. Each exposure starts with the rising edge of the trigger pulse. The range of programmable exposure time and the timing chart of the exposure and the readout are shown below.

	4096pixels_Dual	10.765~12336.176	
	Dragrommable avecaure time	4096pixels_Single	23.000~12336.176
р	Programmable exposure time	2048pixels_Dual	10.941~12336.176
		2048pixels_Single	10.941~12336.176
		4096pixels_ Dual	12.05
		4096pixels_ Single	24.09
r Readout time	2048pixels_ Dual	12.05	
	4096pixels_ Single	12.05	
a Trigger pulse H time		≧2.9	
b	Trigger pulse L time	≧2.9	
	4096pixels_ Dual	≧13.12	
	4096pixels_ Single	≧25.93	
C	c Trigger pulse cycle	2048pixels_ Dual	≧13.43
		2048pixels_ Single	≧13.43

 Table 5-9-2-1
 External Trigger (Trigger Edge) Programmable Exposure Time

(Unit:µs)



#### Figure 5-9-2-1 External Trigger (Trigger Edge) Exposure Mode (In case of 4096 pixels)



#### Figure 5-9-2-2 External Trigger (Trigger Edge) Exposure Mode (In case of 2048 pixels)

#### 5.9.3 External Trigger Exposure Mode (Trigger Level)

In external trigger exposure mode (Trigger Level), the exposure time is determined by the high trigger pulse time, and the line period is determined by the external trigger period. Each exposure starts with the rising edge of the trigger pulse. The range of programmable exposure time, the timing chart of the exposure and the readout are shown below.

		4096pixels_Dual	12.05
	4096pixels_Single	24.09	
ſ	Readout lime	2048pixels_Dual	12.05
		2048pixels_Single	12.05
		4096pixels_ Dual	≧10.22
0		4096pixels_Single	≧23.03
a mgger pulse H ume	2048pixels_Dual	≧10.53	
	2048pixels_ Single	≧10.53	
b	Trigger pulse L time	≧2.9	9
c Trigger pulse cycle	4096pixels_ Dual	≧13.12	
	4096pixels_Single	≧25.93	
	2048pixels_Dual	≧13.43	
		2048pixels_Single	≧13.43

Table 5-0-2-1	ExtornalTriggor/Triggor	Loval) Programmable	Exposuro Timo
1 abie 3-3-3-1		Level) Flogrammable	

(Unit:µs)



Figure 5-9-3-1 External Trigger (Trigger Level) Exposure Mode (In case of 4096 pixels)



Figure 5-9-3-2 External Trigger (Trigger Level) Exposure Mode (In case of 2048 pixels)

#### 5.10 Setting Offset

In the figure below, the horizontal axis indicates the amount of incident light and the vertical axis indicates the output.

Fs shows the output at saturation. Dd shows the output at darkness. (Both Fs and Dd are digital.) Se shows the saturation current, or the amount of exposure when the output saturates.



Figure 5-10-1 Saturation Exposure and Dark Current Output

By setting the offset, you can set the Y-intercept arbitrarily. DF shows the digital offset value. The gradient of the line does not change.



Figure 5-10-2 Offset Adjustment

• Adjust amount of offset in accordance with the requirements of your camera system.

#### 5.11 Setting Gain

The camera can adjust the analog gain (x1 to x17.8) and the digital gain. As shown in the figure below, increasing the gain setting increases the gradient of the camera's response curve and results in a higher camera output for a given amount of light. Analog gain can be changed by setting the "AnalogGain" control register. Digital gain can be changed by setting the "DigitalGain" control register.



Figure 5-11-1 PGA Gain Adjustment

- Gain and noise values are proportionally related.
- Adjust the amount of gain in accordance with the requirements of your camera system.

Gain-Sensitivity is shown below.

AnalogGain	Analog Amplifier		Sensitivity (V/lx • s)
0	x1.0	0.0dB	125
1	x1.8	5.0dB	225
2	x3.4	10.7dB	425
3	x5.2	14.3dB	650
4	x6.4	16.1dB	800
5	x7.8	17.9dB	975
6	x9.7	19.7dB	1213
7	x17.8	25.0dB	2225

#### Table 5-11-1 Gain-Sensitivity

Digital gain x1, Pixel correction:default(Factory white correction data, Correctionlevel 200DN /8-bit)

#### 5.12 Pixel Correction

As a rule, image sensors (CCD, CMOS and so on) have fixed pattern noise and photo response non-uniformity. Lens shading and light sources can also cause non-uniformity. The camera is set to the optimal correction before shipping in order to provide images of the highest grade.

The camera also has a user white correction function to cope with lens shading and non-uniform illumination, or to be able to completely clear the uneven brightness generated by changing the spectral response level of the light source. Cal\_bl: Output data of each pixel at perfectly dark (digital) Cal\_wh: Output data of each pixel in uniform illumination (digital) Target\_Val : Target value for correction (10bit digital) Vin : Input data (digital) Vout : Output data (digital) The corrected data is expressed in the following equation. Vout=(Vin-Cal\_bl) x Target\_val / (Cal\_wh-Cal\_bl)



Figure 5-12-1 Waveform before and after bit correction

#### 5.12.1 How to Perform Pixel Correction

- ① Remove the lens cap and place a white object. Then you can acquire user white correction data. With a lens, the shading by both the lens and the light source will be simultaneously corrected. At this time, please defocus a little to avoid being affected by the non-uniformity of the object.
- 2 Run PixelCorrectDataSave

PixelCorrectDataSave	Execute()	
PixelCorrectDataSaveB	Execute()	

③ Complete PixelCorrectDataSave : Background color is change into white

PixelCorrectDataSave	Execute()
PixelCorrectDataSaveBlack	Execute()

④ Setting PixelCorrectSetLevel (Correction level : 8bit)

LineDelay	0
PixelCorrectSetMode	Factory white
PixelCorrectSetLevel	127
PixelCorrectDataSave	Execute()
PixelCorrectDataSaveB	Execute()

#### 5.13 Test Pattern

This camera can generate a test pattern. Use the test pattern to verify the proper timing and connections between the camera and the frame grabber board.



Figure 5-13-1 Test Pattern of XCM40170DLMT2CXP(4096pixels)



Figure 5-13-2 Test Image of XCM40170DLMT2CXP(4096pixels)

From pixel 0, 10bit data is output in order (0,1, 2, 3  $\dots$  1023, 0, 1, 2), repeating 4 times.

In case of 8bit, data is output in order (0,0,0, 0, 1, 1, 1, 1, 2, 2, 2, 2, 3, 3, 3, 3, ... 255, 255, 255), repeating 4 times.



Figure 5-13-3 Test Pattern of XCM40170DLMT2CXP(2048pixels)



Figure 5-13-4 Test Image of XCM40170DLMT2CXP(2048pixels)

From pixel 0, 10bit data is output in order (0,1, 2, 3 ... 1023, 0, 1, 2), repeating 2 times.

In case of 8bit, data is output in order (0,0,0, 0, 1, 1, 1, 1, 2, 2, 2, 2, 3, 3, 3, 3, ... 255, 255, 255), repeating 2 times.

## **6 Confirming Camera Settings**

#### 6.1 Before Power-on

① Make sure that the pin assignment of the power cable is correct.



No	Name
1	12~15V
2	12~15V
3	12~15V
4	GND
5	GND
6	GND

Figure 6-1-1 Pin Assignment of Power Cable

2 Make sure that the coaxial cables are connected to the frame grabber board correctly as follows.

A 75 $\Omega$ -type coaxial cable and connector must be used. The number of links and usable positions on the frame grabber board varies by board manufacturer.

(In the case of the Matrox Radient eV-CXP there are 4 connectors, and 2 cameras can be connected)

Camera CXP1  $\rightarrow$  Frame Grabber CXP0 Camera CXP2  $\rightarrow$  Frame Grabber CXP1





#### 6.2 After Power-on

Check the camera operation using the camera control software supplied with your frame grabber. For details please refer to your frame grabber's manual.

Capture images using a camera interface board utility. In the case of Matrox's Radient eV-CXP, it is convenient to use Intellicam.





#### 6.3 During Operation

(1) Does an acquisition time out error occur?

<Cause>

<1> Captured images are too large.

If there are many filtering processes, the assignments to the driver may be insufficient.

<2> The cable is detached from the connector

Ensure that the power cable and coaxial cables are connected to the camera firmly.

<3> Coaxial cables are susceptible to noise when the cables are laid near a light source inverter line or a power line. The personal computer in use may freeze and need to be reset.

(2) Are there dark lines in the direction of vertical scanning on the image?

<Cause>

<1> Dust on the sensor window

Dust may get onto the sensor window from the inside or the outside of the camera. Remove the dust with air or a lens cleaner.

## **7 Sensor Handling Instructions**

#### 7.1 Electrostatic Discharge and the Sensor

CMOS sensors are susceptible to damage from electrostatic discharge and can become defective.

#### 7.2 Protecting Against Dust, Oil and Scratches

The CMOS sensor window is part of the optical path and should be handled like other optical components with care. If you use the camera in a dusty area, prepare a dust-proof enclosure. Dust can obscure pixels, producing dark lines on the image.

#### 7.3 Cleaning the Sensor Window

Dust: Can usually be removed by blowing the window surface using a compressed air blower.

Oil: Wipe the window with a lint-free cloth wiper moistened with ethyl alcohol carefully and slowly.

## 8 Troubleshooting

The following pages contain several troubleshooting charts that can help you find the cause of problems user sometimes encounters.

#### 8.1 When there is no Image





#### 8.2 When Noise is present in the Image





#### 8.3 When the Camera becomes hot



## 9 Others

#### 9.1 Notice

- No part of this document may be reproduced in any form, in whole or in part, without the expressed written consent of NED.
- Contents of this document are subject to change without prior notice.
- Every care has been taken in the preparation of this User's Manual. If you should discover any errors or omissions, please notify your nearest NED representative.

#### 9.2 Contact for support

Nippon Electro-Sensory Devices Corporation Head Office 2-5-12, Itachibori, Nishi-ku, Osaka 550-0012, Japan Phone +81-6-6534-5300 Fax +81-6-6534-6080

Tokyo Branch Gibraltar Oi BLDG., Room No.402 1-45-2, Oi, Shinagawa-ku, Tokyo 140-0014, Japan Phone +81-3-5718-3181 Fax +81-3-5718-0331

Nishi-Nippon Branch Twin Square 1-8-28 Enokida, Hakata-ku, Fukuoka, 812-0004, Japan Phone +81-92-451-9333 Fax +81-92-451-9335

URL <u>http://ned-sensor.co.jp/en</u>

E-Mail sales@ned-sensor.com

#### 9.3 Product Support

If there is still a problem with your camera after checking it in accordance with the troubleshooting guide, turn off the power and call your NED representative.

# **Revision History**

Revision	Date	Changes
01	24 March 2016	Initial release